CS 682 - Homework 4

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1 Optical Flow (a)

Instead of W(x), I will denote the neighborhood by W(z) in order to avoid confusing it with the subscript x in I_x and u_x .

$$E(u) = \sum_{W(z)} \left(I_x u_x + I_y u_y + I_t \right)^2$$

The partial derivatives with respect to the two components of u are set to 0:

$$\frac{\partial E}{\partial u_x} = 2 \sum_{W(z)} \left(I_x^2 u_x + I_x I_y u_y + I_x I_t \right) = 0$$
$$\frac{\partial E}{\partial u_y} = 2 \sum_{W(z)} \left(I_x I_y u_x + I_y^2 u_y + I_y I_t \right) = 0$$

The 2 can be ignored. The sums can be split up, with the constants u_x and u_y factored out:

0.77

$$u_x \sum_{W(z)} I_x^2 + u_y \sum_{W(z)} I_x I_y + \sum_{W(z)} I_x I_t = 0$$
$$u_x \sum_{W(z)} I_x I_y + u_y \sum_{W(z)} I_y^2 + \sum_{W(z)} I_y I_t = 0$$

Combining into a single matrix equation:

$$\begin{bmatrix} \sum I_x^2 & \sum I_x I_y \\ \sum I_x I_y & \sum I_y^2 \end{bmatrix} \begin{bmatrix} u_x \\ u_y \end{bmatrix} + \begin{bmatrix} \sum I_x I_t \\ \sum I_y I_t \end{bmatrix} = 0$$

This can be expressed as

$$G\mathbf{u} + \mathbf{b} = 0$$
$$G\mathbf{u} = -\mathbf{b}$$

2 Optical Flow (b)

The solution to the above linear system may be undetermined. Since G is a 2×2 matrix, the only possible scenarios in which G is singular are:

Rank(G) = 1: The neighborhood contains only an edge (1D shape) and therefore a single point from it can be matched with any other point on the edge.

Rank(G) = 0: The neighborhood contains no texture and therefore a single point can be matched with any other point.