Event Based Community Detection for Networks

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Motivation

Given a dynamic network and a set of events for which the network is known to be responsible, it is natural to ask questions about which nodes participated in the events. Uncovering this information reveals details about the network’s activity, such as which nodes are most responsible for the network’s past activity.
Motivation

Given a dynamic network and a set of events for which the network is known to be responsible, it is natural to ask questions about which nodes participated in the events. Uncovering this information reveals details about the network’s activity, such as which nodes are most responsible for the network’s past activity.

Objective

Given a dynamic network and a set of events, for each node, we would like to determine a subset of events in which that node participated.
Assumptions

- Our primary assumption is that nodes who are involved with an event will have an anomalous neighborhood network structure around the time of the event.
- The event set will be sparse (i.e. there will be few events).
- Nodes who have worked together in the past will likely work together again at some point in the future.
- A node’s usual behavior remains relatively constant during the course of observation.
Network & Event Notation

- Let $G_t = (V, E_t)$ be a weighted, directed graph at time $t \in \{1, 2, ..., T\}$ with a set of nodes $V$ and weighted edges $E_t$.
- Let $w_t(v_1, v_2) \in \mathbb{N}$ denote the weight of the edge from node $v_1 \in V$ to $v_2 \in V$ at time $t$. If there is no such edge, $w_t(v_1, v_2) = 0$.
- For $v \in V$ let $\Gamma_t(v)$ be the set of neighbors of $v$ and $E_t(v)$ be the set of edges connected to $v$ at time $t$.
- Let $A = \{a_1, a_2, ..., a_k\}$ be an event set where $a_i$ denotes the time of event $i$ and $1 \leq a_1 < ... < a_i < ... < a_k \leq T$. 
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Structural-EPD

**Structural Event-Participation Detection**

Seeks to find anomalous neighborhood structure by looking for times when a node either changed who it was communicating with or the frequency with which it was communicating with other nodes.

Thus, for node $v$, we are looking for anomalies in the set $\Gamma_t(v)$ and/or the sets $\{w_t(v, u) : u \in V(G)\}$ and $\{w_t(u, v) : u \in V(G)\}$ for $t$ near event times.
Methods for S-EPD

There are many ways to model the communication of a node’s neighborhood. Two methods will be discussed here.

- Counting Process for each potential edge
- Distance from Median Graph
This approach models the communication between a pair of nodes *during non-event times* as a counting process.

Since, at any given time, most nodes do not communicate with each other, we will employ a hurdle model.

We model $w_t(u, v) = 0$ and $w_t(u, v) > 0$ using a binomial distribution (similarly for $w_t(v, u)$).

For $w_t(u, v) > 0$, we model $w_t(u, v)$ using a shifted geometric distribution with

$$p = 1 - \frac{E[w_s(u, v)]}{1 + E[w_s(u, v)]} \text{ with } s \in \{ t : w_t(u, v) > 0, t \notin A \}$$

$$P(w_t(u, v) = k) = \left( \frac{E[w_s(u, v)]}{1 + E[w_s(u, v)]} \right)^{k-1} \left( 1 - \frac{E[w_s(u, v)]}{1 + E[w_s(u, v)]} \right)$$
Below is an example of the counting process model for communication between two nodes.

(a) Realized

(b) Hurdle Model
For node $u$, let $C_t : V \rightarrow \mathbb{N}^{n-1}$ be the map which gives the number of times $u$ communicated with each $v_i \in V$ at time $t$ (i.e. $C_t(u) = \{c_{v_1}, c_{v_2}, ..., c_{v_k}\}$ where $c_{v_i}$ is the number of times $u$ communicated with $v_i$ at time $t$).

For each $c_{v_i}$, we calculate $P(w_t(u, v_i) = c_{v_i})$, the probability that $u$ communicates with node $v_i$ $c_{v_i}$ times.

Assuming communication rates from node to node are independent, we find the joint probability $P(C(u) = C_t(u)) = \prod P(w_t(u, v_i) = c_{v_i})$, the probability that this communication structure would occur.

Unusually low probabilities are considered indicative of anomalous neighborhood network structure.
Definition: Edit Distance

Given two graphs $G$ and $G'$, each with the same number of vertices, the edit distance $D : G \times G \to \mathbb{N}$ between $G$ and $G'$ is defined as

$$D(G, G') = |E(G) \triangle E(G')| = |(E(G) \setminus E(G')) \cup (E(G') \setminus E(G))|.$$ 

Note that,

$$D(G_1, G_3) = |E(G_1) \triangle E(G_3)| = |[E(G_1) \triangle E(G_2)] \triangle [E(G_2) \triangle E(G_3)]| \leq |E(G_1) \triangle E(G_2)| + |E(G_2) \triangle E(G_3)| = D(G_1, G_2) + D(G_2, G_3)$$

Therefore, $D$ is a metric (the other two conditions are obvious) and the space of graphs can be considered a metric space.
S-EPD: Distance from Median Graph

Definition: Median Graph

The median graph $\overline{G}_H$ of a set of graphs $H = \{G_1, G_2, ..., G_m\}$ each with $n$ vertices is defined as,

$$\overline{G}_H = \arg\min_{G \in \mathcal{G}_n} \sum_{G_i \in H} D(G, G_i)$$

where $\mathcal{G}_n$ is the set of all graphs constructible from $n$ vertices.
Framed for our problem,

- Let $H$ be the set of graphs during which events did not occur. We first calculate the median graph, $\overline{G}_H$, of $H$.
- Then for every graph $G_t$ with $t \in \{1, 2, \ldots, T\}$, we calculate $D(G_t, \overline{G}_H)$, the edit-distance between the graph and the median graph.
- Times with significantly large edit-distances are considered anomalous. We search for nodes which exhibit anomalous neighborhood structure around the time of events.
S-EPD Example

In this example, the plots show the communication rates of two nodes. The node on the left was involved with an activity (going on vacation) around times 32-38 while the node at the right acted normally during the period of interest. Note that the total communication rate remained relatively constant (this employee continued working while on vacation), but the rates between individuals changes.
Metric-EPD

While structural EPD examines the communication behavior of a particular node, metric EPD determines how the role of a node changes through time. Using SNA metrics, we can look for anomalous positioning in the network as well as local neighborhood structure.
Methods for M-EPD

Example SNA metrics:

- Anomalous tie-strength (Adamic & Adar):

\[
TS(u, v) = \sum_{w \in \Gamma(u) \cap \Gamma(v)} \frac{1}{\log|\Gamma(w)|}
\]

- Anomalous Jaccard Index:

\[
J(u, v) = \frac{|\Gamma(u) \cap \Gamma(v)|}{|\Gamma(u) \cup \Gamma(v)|}
\]

- Anomalous betweenness centrality,

\[
g(v) = \sum_{u \neq v \neq w} \frac{\sigma_{uw}(v)}{\sigma_{uw}}
\]

where \(\sigma_{uw}(v)\) is the number of shortest paths from \(u\) to \(w\) which pass through \(v\) and \(\sigma_{uw}\) is the number of shortest paths from \(u\) to \(w\).
Tie-Strength Metrics

- Given a set of network members $N$ and a set of events $A$, we can construct a bipartite graph $EP = (V, E)$ with $V \subseteq N \cup A$ and $E \subseteq N \times A$.
- An edge exists between a network member and an event when the network member is believed to have participated in that event.
- For tie-strength, we use the Adamic & Adar tie-strength metric,

$$TS(u, v) = \sum_{e \in \Gamma(u) \cap \Gamma(v)} \frac{1}{\log |\Gamma(e)|},$$

where $\Gamma(u)$ is the neighborhood of node $u$ (i.e. the events in which $u$ participated).
We construct a weighted graph $G_{TS}$ where the nodes are the members of the network and where the weight of an edge $\{v_1, v_2\}$ of $G_{TS}$ is the tie-strength between $v_1, v_2$.

Running a clustering algorithm on this weighted graph produces a list of clusters of nodes who participated in the same events.

I will give a brief overview of the *Shrink-H* clustering algorithm.
Shrink Clustering

Modularity ($Q$): the fraction of the edges that fall within the given groups minus the expected such fraction if edges were distributed at random.

**Structural Similarity**

Given a graph $G = (V, E)$, let $\Gamma(u)$ denote the neighborhood of $u \in V$. Then the *structural similarity* $\gamma(u, v)$ of two nodes $u, v \in V$ is given by,

$$
\gamma(u, v) = \frac{\sum_{x \in \Gamma(u) \cap \Gamma(v)} w(u, x)w(v, x)}{\sqrt{\sum_{x \in \Gamma(u)} w^2(u, x)} \sqrt{\sum_{x \in \Gamma(v)} w^2(v, x)}}
$$

The Shrink-H algorithm combines nodes with high structural similarity into “supernodes” (and in turn combines supernodes with high structural similarity) until the modularity gain $\Delta Q$ becomes negative.
Shrink Clustering: A Picture

(a) 1st iteration

(b) 2nd iteration

stop when $\Delta Q_s < 0$
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Results
So far we have the following:

- Anomaly scores for each node at each time period.
- For each event, a list of nodes that are predicted to have participated in that event.
- Clusters of nodes that work together.

The obvious next step is to track how anomalous these clusters are behaving in the hope of predicting when the cluster might produce another event.
Cluster Anomaly Scores
For each cluster $i$, we aggregate the anomaly scores of the involved nodes using a logistic regression model,

$$CS_i(y) = \frac{e^y}{e^y + 1},$$

where $y = \alpha_0 + \alpha_1 x_1 + \alpha_2 x_2 + \ldots + \alpha_n x_n$ and $x_1, \ldots, x_n$ are the anomaly scores for the nodes in the cluster.
In this framework, $\alpha_j$ represents how much node $j$’s behavior impacts the cluster’s event rate.
Network Anomaly Scores

Then for the Network Activity Score, we perform another logistic regression with all the events as the dependent variable,

$$NS(z) = \frac{e^z}{e^z + 1},$$

where $z = \beta_0 + \beta_1 CS_1 + \beta_2 CS_2 + \ldots + \beta_m CS_m$ for cluster anomaly scores $CS_1, CS_2, \ldots, CS_m$.

In this framework, $\beta_i$ represents how much cluster $i$’s behavior impacts the network’s event rate.
Network Activity Prediction

Tracking these scores over time will hopefully give us an indication of when future events might occur (i.e. some important clusters are beginning to act anomalously).
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5. Results
Results: DCNS

(e) Run 1

(f) Run 2
Results: GeoEye Email Network
References
